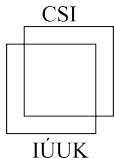


# Parameterized complexity of fair deletion problems II.

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## Deletion problems

Given a graph property  $P$  and graph  $G$ , vertex (edge) **deletion problem** is a task of finding set  $S$  of vertices (edges) such that  $G \setminus S$  satisfies  $P$ .

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### Examples:

- Vertex Cover –  $W \subseteq V$  such that  $G \setminus W$  has no edges.
- Feedback Vertex set –  $W \subseteq V$  such that  $G \setminus W$  is a forest.
- Feedback Arc set –  $F \subseteq E$  such that  $G \setminus F$  is a DAG.
- Odd cycle transversal –  $W \subseteq V$  such that  $G \setminus W$  is a bipartite.
- Odd edge cycle transversal –  $F \subseteq E$  such that  $G \setminus F$  is a bipartite.

For monotone properties finding any such set is trivial.

Usual aim is to find the **smallest** such set.

## Fair deletion problems

Usually aim is to find **smallest** set  $S$  such that  $G \setminus S$  satisfies  $P$ .

In **Fair** deletion problems, we want to find set that is “**locally**” small.

- For a set  $F$  of **edges**, we want to **minimize**

$$\max_{v \in V} \deg_F(v).$$

- For a set  $W$  of **vertices**, we want to **minimize**

$$\max_{v \in V} |N(v) \cap W|.$$

## Parameterized complexity

In parameterized complexity in addition to the input, we have a number called **parameter**.

Examples of parameters:

- size of the solution
- **structural parameters** (treewidth, clique width, vertex cover...)

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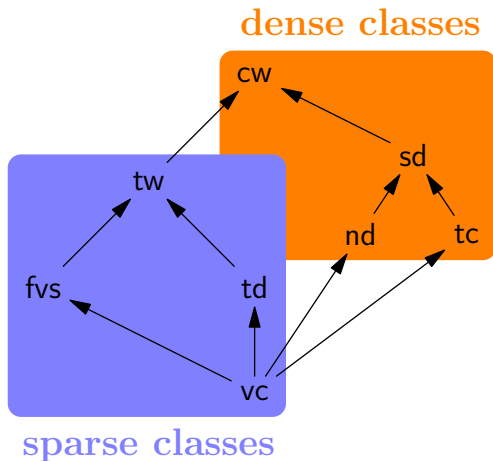
- size of the solution
- **structural parameters** (treewidth, clique width, vertex cover...)

The running time is described as a function of both the size of the input and the parameter.

### Complexity classes

- **FPT** – class of problems solvable in time  $f(k)n^c$
- **XP** – class of problems solvable in time  $n^{f(k)}$
- **W[1]-hard** – class of problems that unlikely admit an FPT alg.

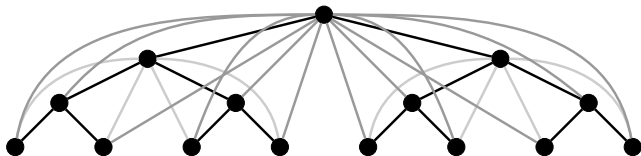
# Overview of structural parameters



# Tree depth

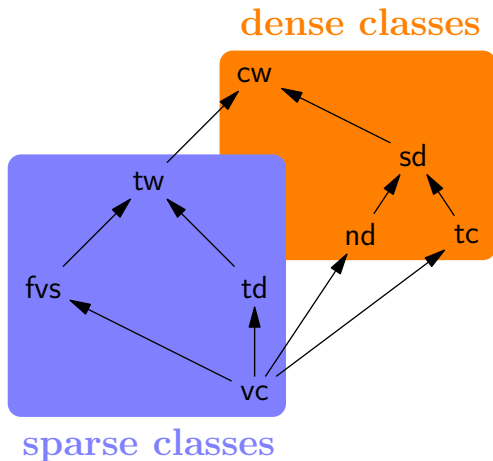
## Definition (Tree depth)

- The **closure**  $Clos(F)$  of a forest  $F$  is the graph obtained from  $F$  by making every vertex adjacent to all of its ancestors.
- The **tree depth**, denoted as  $td(G)$ , of a graph  $G$  is one more than the minimum height of a rooted forest  $F$  such that  $G \subseteq Clos(F)$ .





# Overview of structural parameters

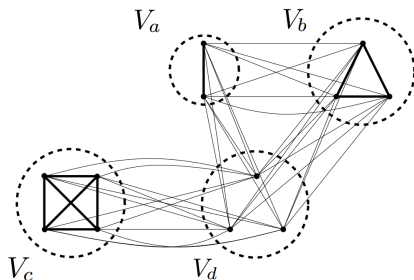


# Neighborhood diversity

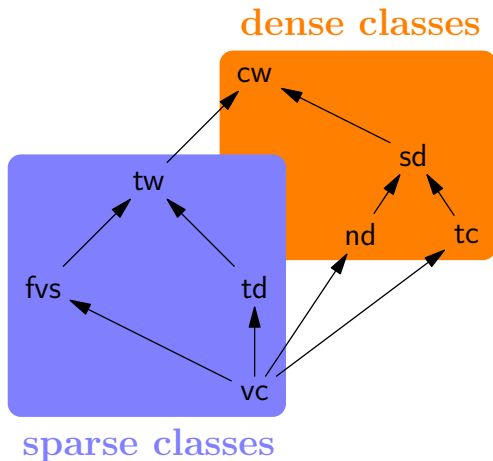
## Definition (Neighborhood diversity)

The **neighborhood diversity** of a graph  $G$  is denoted by  $\text{nd}(G)$  and it is the minimum size of a partition of vertices into classes such that all vertices in the same class have the same neighborhood, i.e.

$N(v) \setminus \{v'\} = N(v') \setminus \{v\}$ , whenever  $v, v'$  are in the same class.



# Overview of structural parameters



# Graph properties

We study properties definable in graph logic ( $\text{FO}$ ,  $\text{MSO}_1$ ,  $\text{MSO}_2$ ).

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Sometimes we want to put **additional restriction** on the deleted set itself (for example Connected vertex cover)

We use an **MSO** formula with one **free set variable**  $S$  such that  $G \models \varphi(S)$  (in contrast to original  $G \setminus S \models \psi$ ).

We call that **generalized deletion problem** or some authors use monadic second order evaluation.

# Fair Vertex Cover

## Problem formulation

Formulated as a Fair Vertex Deletion problem: Find a set of vertices  $W$  such that the rest of the graph **has no edges**.

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## Our results

- **FPT** algorithm for the Fair vertex cover problem parameterized by **modular width**.  
(D. Knop, TM, T. Toufar 2017+)
- The Fair vertex cover problem is **W[1]-hard** parameterized by **tree depth + feedback vertex set**.  
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## Known results

- An **XP** algorithm for the generalized version of the Fair  $\text{MSO}_2$  edge deletion problem parameterized by treewidth ( $f(|\varphi|)n^{O(\text{tw}(G))}$ ).  
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Kolman, Lidický, and Sereni
- Can be easily adapted to the vertex version.
- $\text{MSO}_2$  does **not admit XP algorithm** on cliques unless standard complexity assumption fails by Lampis or Courcelle, Makowsky and Rotics.

## Our results — Vertex deletion problem

### Positive results

- **FPT** algorithm for generalized version of Fair  $\text{MSO}_1$  vertex deletion problem parameterized by **neighbourhood diversity**. (TM, T. Toufar 2017)
- **FPT** algorithm for generalized version of Fair  $\text{MSO}_1$  vertex deletion problem parameterized by **twin cover**. (D. Knop, TM, T. Toufar 2017+)

## Our results — Vertex deletion problem

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### Hardness results

- The Fair vertex cover problem is  **$\text{W}[1]$ -hard** parameterized by **tree depth + feedback vertex set**. (D. Knop, TM, T. Toufar 2017+)

## Our results — Edge deletion problem

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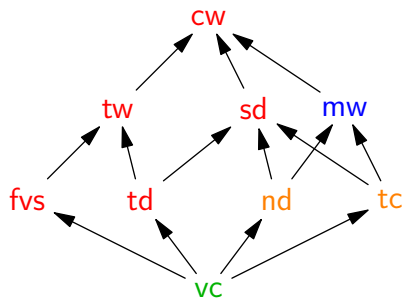
### Positive results

- **FPT** algorithm for generalized version of Fair  $\text{MSO}_2$  edge deletion problem parameterized by **vertex cover**.  
(TM, T. Toufar 2017)

### Hardness results

- FO Fair deletion is **W[1]-hard** with respect to **tree depth + feedback vertex set size**.  
(TM, T. Toufar 2017)

## Overview of the results



**Green** means FPT algorithm for  $\text{MSO}_2$  edge deletion problem.

**Orange** means FPT algorithm only for  $\text{MSO}_1$  vertex deletion problem.

**Red** means hardness results for both edge and vertex deletion problem.

**Blue** means it is mostly unknown.

## Open questions

- Is there a “basic” **edge deletion** problem such that it is **W[t]-hard** on graphs of bounded **tree depth, feedback vertex set or shrub depth**?

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Thank you for your attention!