

# Simplified Algorithmic Metatheorems Beyond MSO

## Treewidth and Neighborhood Diversity

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# Monadic Second Order Logic – MSO<sub>1</sub>

- universe is a graph
- variables for elements (vertices, edges)
- variables for sets of vertices

x,y

X,Y

$$\begin{aligned}
 (\exists R, G, B) (R \cup G \cup B = V) \wedge (\forall u, v \in R \rightarrow \{u, v\} \notin E) \\
 \wedge (\forall u, v \in G \rightarrow \{u, v\} \notin E) \\
 \wedge (\forall u, v \in B \rightarrow \{u, v\} \notin E)
 \end{aligned}$$

## MSO<sub>2</sub>

- adds a possibility for variables for sets of **edges**
- model checking is hard on graphs of bounded neighborhood diversity

# Monadic Second Order Logic

## Theorem (Courcelle)

*There exists an algorithm that, given*

- *an MSO formula  $\varphi$ , and*
- *an  $n$ -vertex graph  $G$  with its tree decomposition of width  $t$  and evaluation of all the free variables of  $\varphi$ ,*

*verifies whether  $\varphi$  is satisfied in  $G$  in time  $f(|\varphi|, t) \cdot n$ .*

- $\varphi$  in prenex form
- $|\varphi|$  is the number of quantifiers in  $\varphi$

# Extending MSO – Local Cardinality Constraints

- linear optimization      FPT(tw)      [Arnborg, Lagergren and Seese 91]
- further objectives      FPT(tw)      [Courcelle and Mosbah 93]
- fair objective function      XP(tw)      [Kolman, Lidický and Sereni 09]
  - given MSO formula  $\varphi(X)$  with a free vertex set variable  $X$
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$$\min_{X \subseteq V} \max_{v \in V} \{X(v) \mid \varphi(X)\}$$

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- W[1]-hard(tw)      FPT(nd)      [Masařík, Toufar 16]

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- add a “global” relation  $[|X| \geq |Y|^2]$
- cardinality constraints FPT (nd) [Ganian, Obdržálek 11]

## Equitable $k$ -Coloring

**Input:** graph  $G = (V, E)$

**Task:** find a partition  $V_1, \dots, V_k$  of  $V$  such that  $G[V_i]$  is an edgeless graph and  $||V_i| - |V_j|| \leq 1$  or report that no such partition exists

$\text{MSO}_{\text{lin}}^G$  only **linear relations** added

$\text{MSO}^G$  general relations added

$$|X| \leq |Y| + 7; |Y| = 2|X|$$

$$|X|^2 + |Y|^3 = |Z|$$

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Indeed, we can combine all possible extensions!

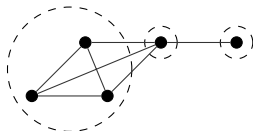
# Neighborhood Diversity

We say that two (distinct) vertices  $u, v$  are of the same *neighborhood type* if they share their respective neighborhoods, that is when

$$N(u) \setminus \{v\} = N(v) \setminus \{u\}.$$

## Definition (Lampis 12)

A graph  $G = (V, E)$  has *neighborhood diversity* at most  $w$  ( $\text{nd}(G) \leq w$ ) if there exists a partition of  $V$  into at most  $w$  sets such that all the vertices in each set have the same neighborhood type.



# Extending MSO – Our Results

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# Vertex Cover – Hardness Reduction

*k*-MULTICOLORED CLIQUE

*Parameter: k*

**Input:** *k*-partite graph  $G = (V_1 \dot{\cup} \dots \dot{\cup} V_k, E)$ , where  $V_a$  is an independent set for every  $a \in [k]$ .

**Task:** Find a clique of size *k*.

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## LCCSUBSET

**Input:** Graph  $G = (V, E)$  with  $|V| = n$  and a function  $f: V \rightarrow 2^{[n]}$ .

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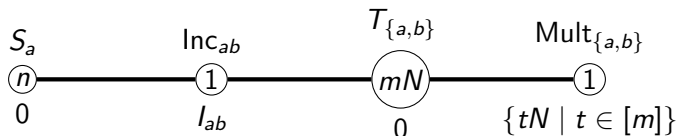
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# Neighborhood Diversity – $\text{MSO}_{\text{lin}}^{\text{GL}}$

- let  $\varphi$  be a  $\text{MSO}_{\text{lin}}^{\text{G}}$  formula with free set variables  $X_1, \dots, X_\ell$
- $\varphi$  contains  $q_s$  set quantifiers and  $q_e$  element quantifiers
- let  $G = (V, E)$  be a graph with  $\text{nd}(G) = \nu$  with types  $T_1, \dots, T_\nu$

## Definition

Let  $\mu: \{X_1, \dots, X_\ell\} \rightarrow 2^V$  be a variable assignment. The **signature of  $\mu$**  is a mapping from  $S_\mu: [\nu] \times 2^{[\ell]} \rightarrow \mathbb{N}$  defined by  $S_\mu(j, I) = |\bigcap_{i \in I} \mu(X_i) \cap T_j|$ .

## Lemma (Lampis 12)

*Suppose that  $\mu, \mu'$  are two variable assignments such that for every  $I \subseteq [\ell], j \in [\nu]$  we have either*

- $S_\mu(j, I) = S_{\mu'}(j, I)$ , or
- both  $S_\mu(j, I), S_{\mu'}(j, I) > 2^{q_s} \cdot q_e$ .

*It follows that  $G, \mu \models \varphi$  if and only if  $G, \mu' \models \varphi$ .*

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Theorem (Lenstra 83, Frank&Tardos 87)

*Let  $p$  be the number of integral variables in a (mixed) integer linear program and let  $L$  be the number of bits needed to encode the program. Then it is possible to find an optimal solution in time  $O(p^{2.5p} \text{poly}(L))$ .*

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- ③ Our CSP have two types of constraints hard ( $\mathcal{H}'$ ) and soft ( $\mathcal{S}$ ).
- ④ We show that if  $\mathcal{H}'$  and  $\mathcal{S}$  have the **local scope property** (the scope of all constraints is restricted to variables corresponding to the descendants of some node of the treedecomposition), it is possible to add new constraints derived from  $\mathcal{H}'$  and  $\mathcal{S}$  to instance  $J'$  which results in instance  $J$ , such that  $J$  is an extension of  $I$ .

# Conclusions

Open problems:

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